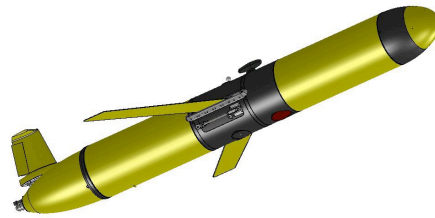
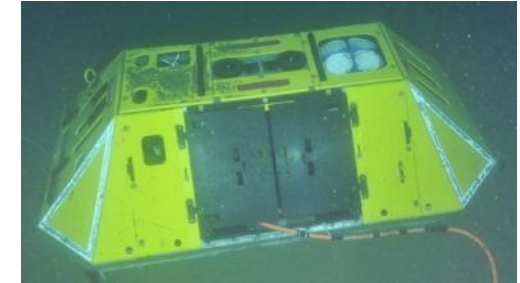




Ocean Observatories Initiative



May 7, 2018



The Endurance Array

Jack Barth (Project Scientist), Ed Dever (Project Manager/Principal Investigator),
Jon Fram (Systems Engineer), Bob Collier (former Project Manager/Principal Investigator)

Chris Wingard, Craig Risien, Linda Fayler, Tully Rohrer, Stuart Pearce, David Neiman, Russ
Desiderio, Johna Winters, Jeff Woods, Jonathan Whitefield, Ian Black

... in collaboration with our WHOI (buoys, design, etc.), UW (cabled infrastructure) and
Rutgers/Raytheon (CyberInfrastructure) colleagues

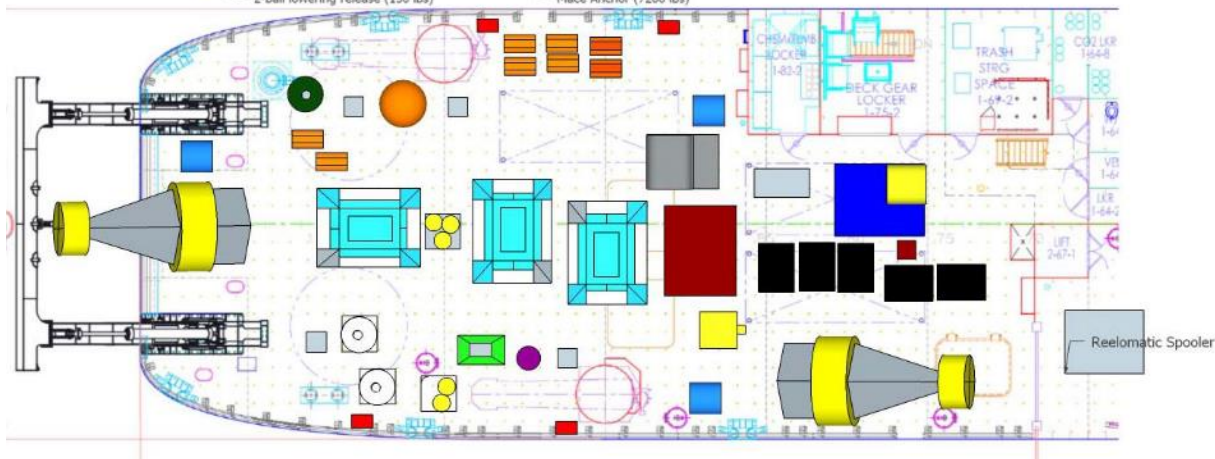
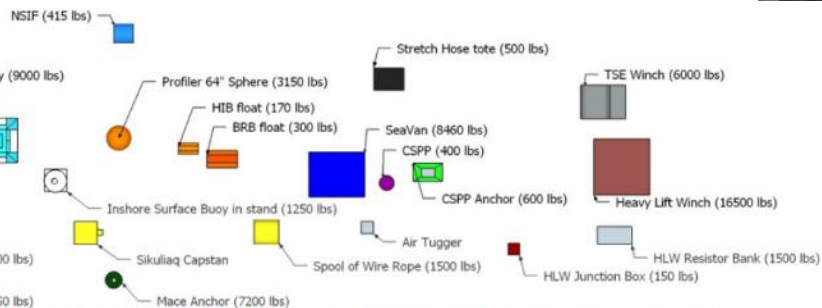
barth@ceas.oregonstate.edu
jfram@ceas.oregonstate.edu

eever@ceas.oregonstate.edu

Endurance Array Turn Cruise

R/V Sikuliaq

March 24 – April 8, 2018



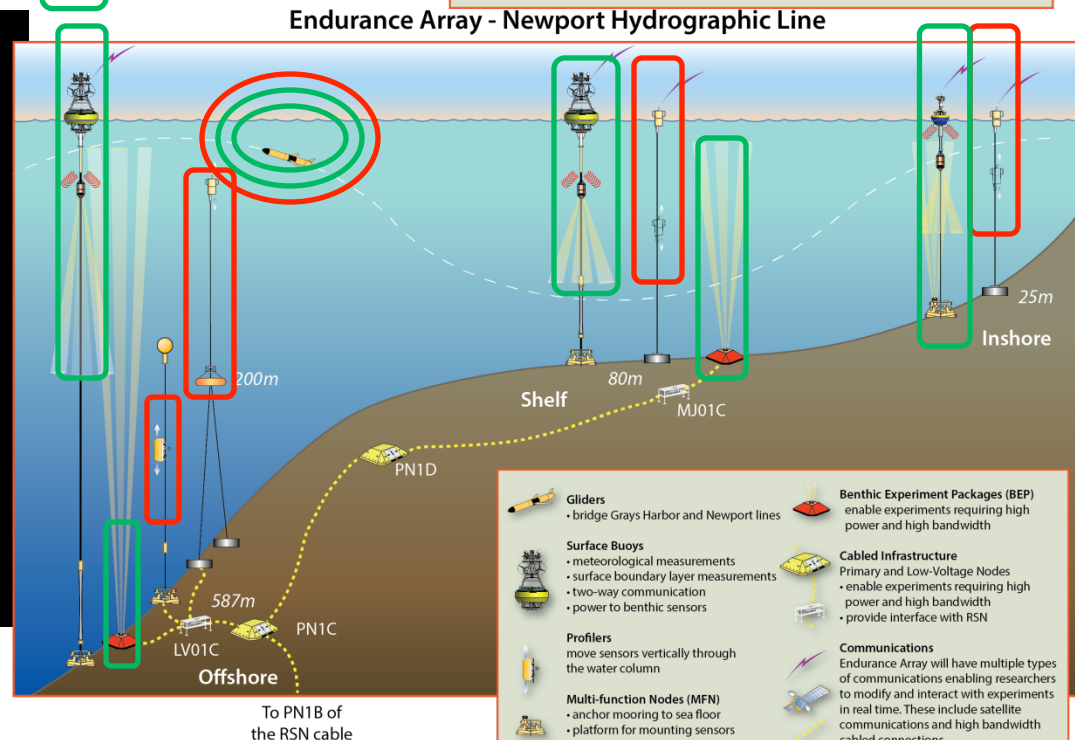
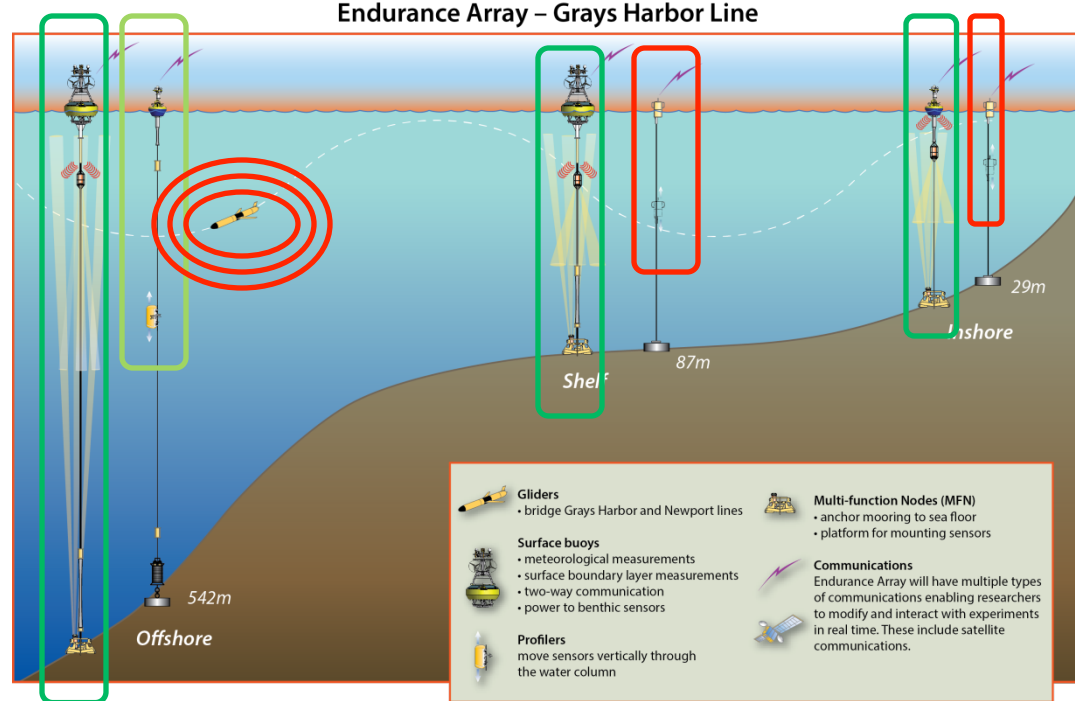
Endurance Array Platform Status

Operating

Not telemetering, but sampling

Not deployed or not working

- All deployed platforms deployed with full complement of instruments.
- Of telemetering uncabled platforms, 10 of 159 instruments not working.



Not telemetering, but sampling

- CE01ISSM NUTNR, NSIF VELPT, ZPLSC, VEL3D, buoy CTD, FLORT, MFN ADCP, PCO2W, PHSEN, PRESF
- CE06ISSM buoy CTD, FLORT, ZPLSC, ADCP, PCO2W, PHSEN, PRESF, VEL3D

Reduced sampling

- CE09OSSM, CE07SHSM

Deployed, failed

- CE01ISSM SPKIR
- CE02SHSM FDCHP
- CE09OSPM FLORT
- CE09OSSM WindSonic (all METBK out)

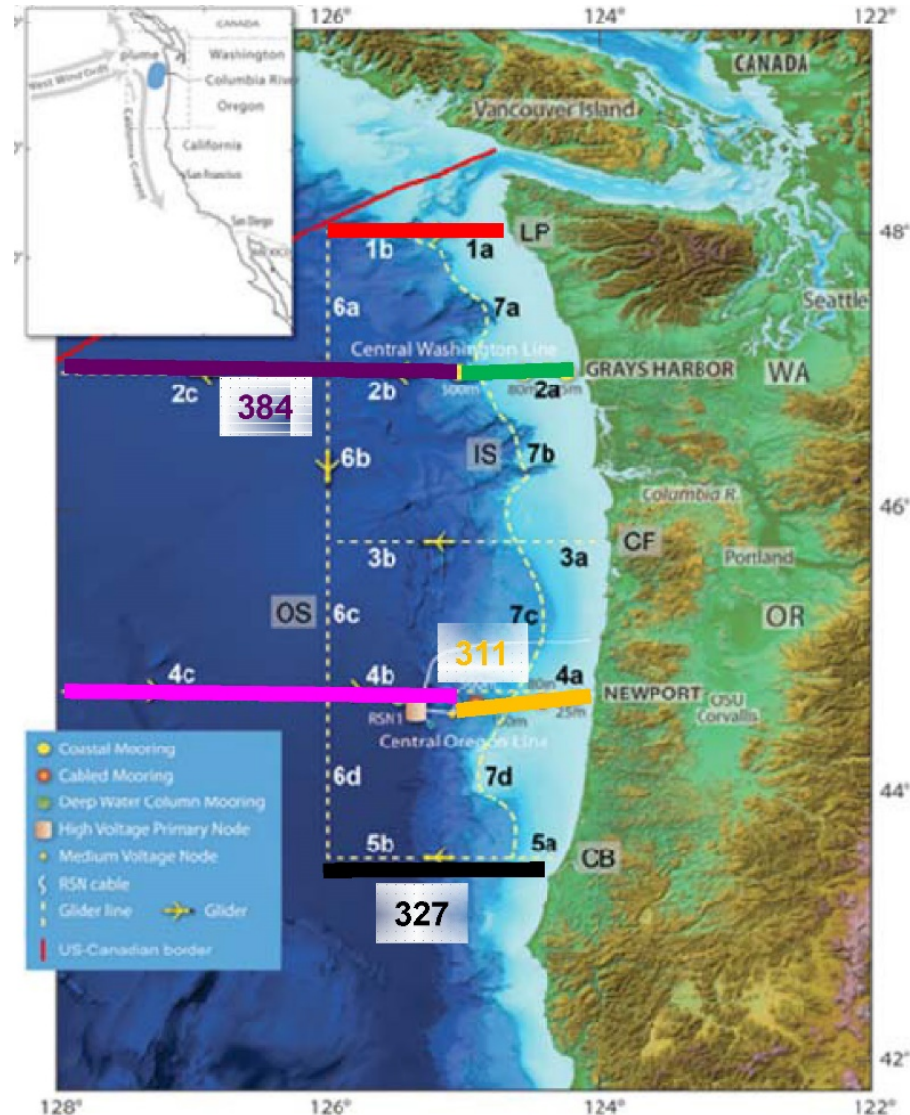
To PN1B of the RSN cable

Endurance Array Glider Coverage

Since Sep 2017 meeting:

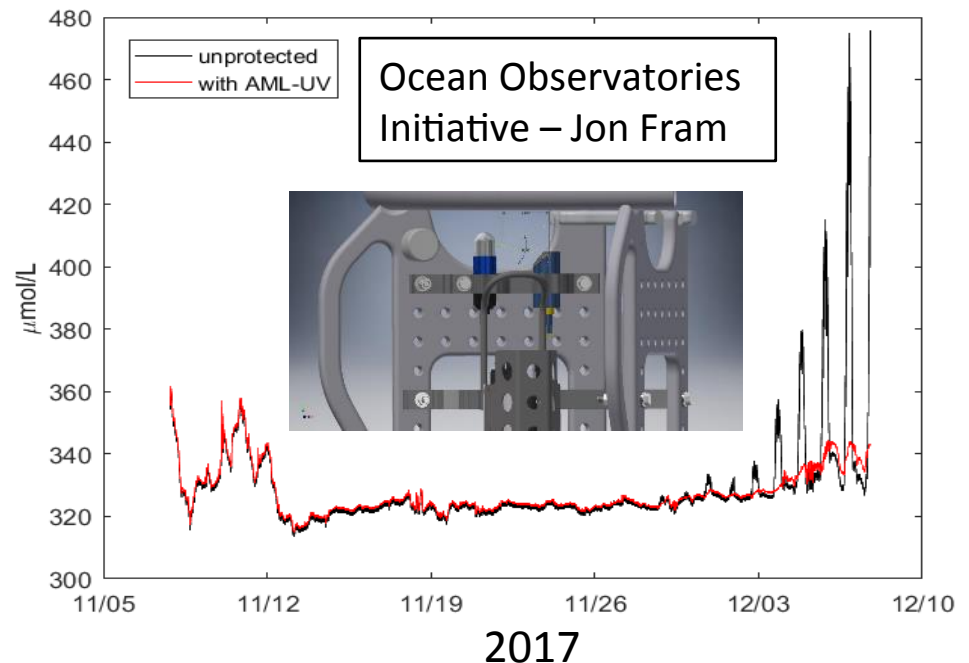
- One partial deployment (3 gliders) starting 7 Dec 2017
- Glider deployments scaled back while memorandum of negotiation (MoN) was prepared by OSU and approved by COL and NSF. This MoN was necessary to continue glider refurb by TWR
- Two gliders presently deployed and at sea operating normally
- Two gliders to be deployed this week (10 May 2018)

Type	Geographic Description
Shallow	Newport Shelf (4a)
Deep	Newport Offshore (4b, 4c)
Shallow	Coos Bay (5a, 5b)
Shallow	Grays Harbor Shelf (2a)
Deep	Grays Harbor Offshore (2b, 2c)
Deep	La Push (1a, 1b)



Notable Technical Progress

- NUTNR: ISUS replaced with SUNA V2 for all deployments starting spring 2018.
- UV antifouling on DOSTA & CAMDS testing fall 2017, worked, reported on at Ocean Sciences 2018, procured for DOSTA and CAMDS, and will be procured for SPKIR
- All telemetered data available on internal ERDDAP server (will be utilized by OMS++)



Challenges

- Instruments
 - Continued CAMDS problems. Only one working.
 - OPTAA service continues to be slow. Will be three short this fall. SeaBird recently hired additional technicians.
 - Problems with other instruments mitigated or on path to resolution
- Heavy Lift Winch Repaired. Spare parts procured. Used successfully on Fall 2017 and Spring 2018 cruises. Some continuing issues with lineout readouts.
- power constraints. May need to adjust sampling.
- Transition
 - Need clarity on long-lead item & service purchases that cross transition time boundaries

Ancillary/data verification activities

Using multi-frequency hull-mounted acoustic sensors to do bioacoustic surveys near moorings (Mei Sato – U. British Columbia with EA group)

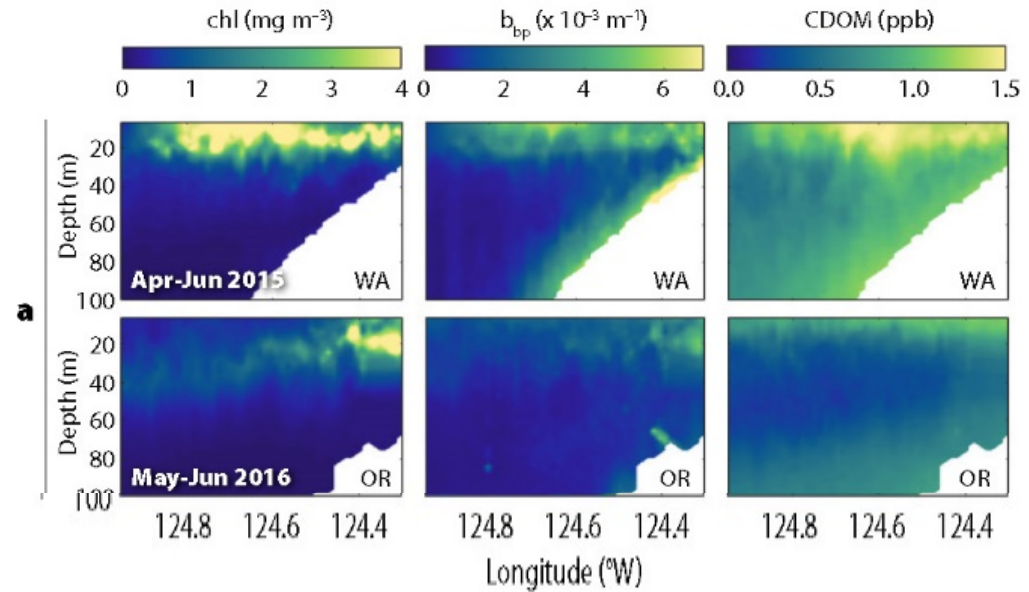
Science Results

Three articles in *Oceanography* OOI special issue:

Temporal and Spatial Dynamics of Physical and Biological Properties along the Endurance Array of the California Current Ecosystem (*Henderikx Freitas, et al.*)

Warm Blobs, Low-Oxygen Events, and an Eclipse: The Ocean Observatories Initiative Endurance Array Captures Them All (*Barth et al.*)

Power from Benthic Microbial Fuel Cells Drives Autonomous Sensors and Acoustic Modems (*Reimers et al.*)



Issues for OOIFB

- We are making progress with technical advances through the OOI ECR process ... but we need to be planning a “tech refresh” strategy (sensors, instruments, platforms, ...)
- Now that field operations are becoming more “routine” we need to turn more eyes to performance metrics across the OOI and data quality
- Engaging external subject matter experts, students, and ancillary projects is extremely valuable and a win-win-win; we need to keep working to make this happen